

The fitter must provide 1 keyset at each (site) address.

This set of spanners comprises two YU.Access Ergonomic Plus and one YU.Access Magnet 25.

The Ergonomic is a lifting tool that enables end users to lift a floor hatch without having to adopt an unnatural posture that is uncomfortable for the back.

The YU.Access Ergonomic Plus is a composition of the hoisting rope in combination with a steel O-ring and a carabiner.

The lifting rope is a bifurcation with 3 loops, each of which has 5 reinforcement seams.

The combination of the O-ring and the carabiner makes this Ergonomic Plus the ideal tool for the YU.Premium covers.

A magnet is required for the DCT application. To that end we use a pot magnet and key ring in which the universal colour code for covers is incorporated.

Moreover, this kit also includes a protective rubber cap for the magnet.

MATERIAL PROPERTIES (ERGONOMIC PLUS)

Material hoisting rope:	Weave nylon
Material O-ring:	Galvanised steel Q195
Material carbiner:	Galvanised steel Q195
Capacity:	90 Kg / lifting element

MATERIAL PROPERTIES MAGNET

Material:	NdFeB
Coating:	Nickel-plated (Ni)
Magnetisation:	N38
Pot diameter D:	25 mm
Total height with hook:	30 mm
Strength:	approx. 18 kg
Max. working temperature:	80°C
Gewicht:	29 g

Pollutant-free according to RoHS Directive 2011/65/EU.

Exempt from registration according to REACH.

Total weight : 520 g

WARRANTY PROVISION

If a component fails to operate correctly or should become faulty under normal use and within a period of one year from its date of installation, said component shall be repaired or replaced free of charge.

The following shall be excluded from this warranty provision:

- ▶ Improper application
- ▶ Transport damage
- ▶ Improper assembly
- ▶ Infringements of component and/or maintenance instructions.

APPLICATIONS

This Ergonomic Plus kit and magnet has been developed for all applications like the YU.Premium & YU.Design which make no longer use of the threading and bolt combination in the lifting mechanism of a manhole cover